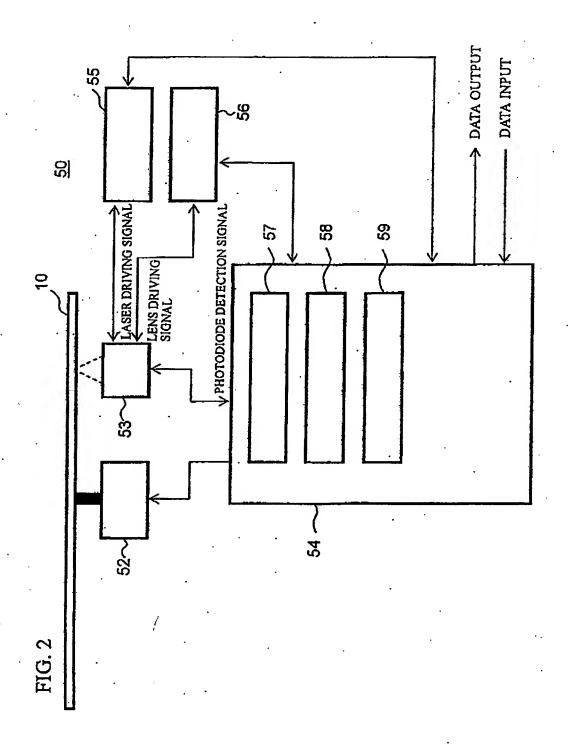
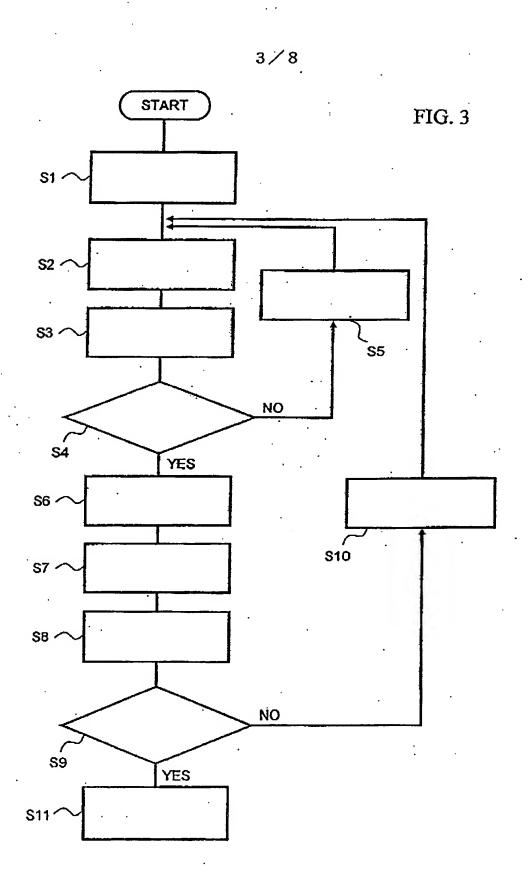
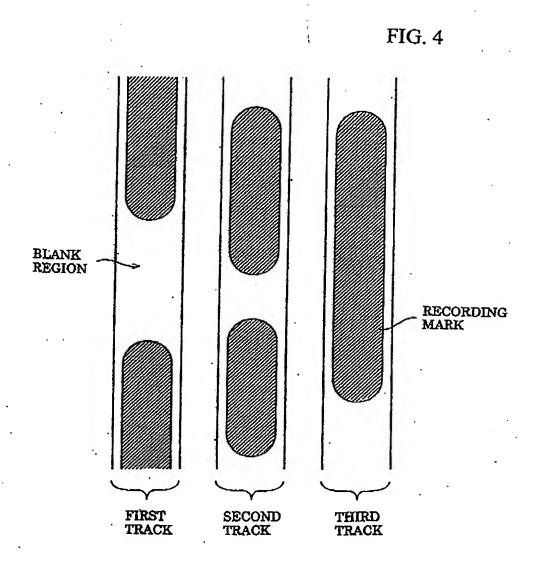


FIG.









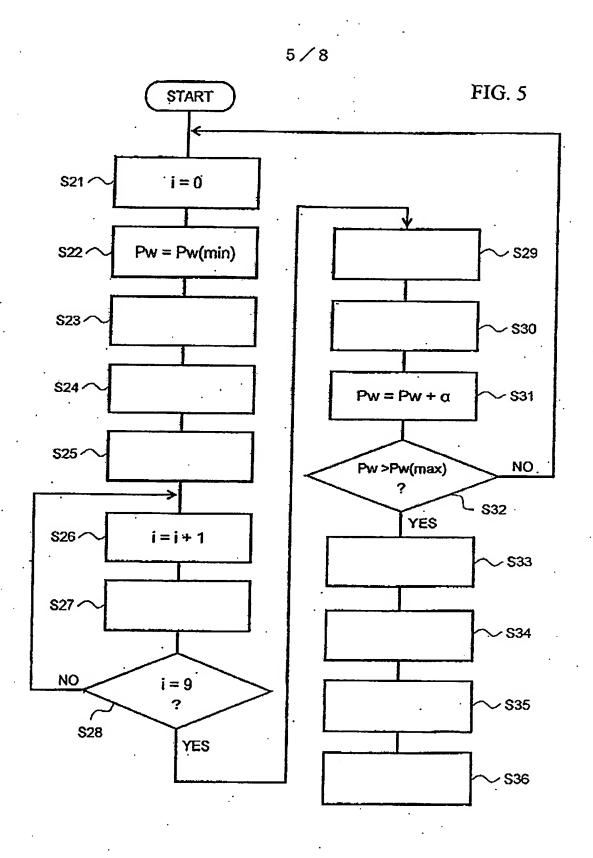


FIG. 6

•			•
	R1	R2	R3
Pw = Pw(min)	*****	*****	. *****
$Pw = Pw(min) + \alpha$	*****	*****	****
	:	•	
Pw = Pw(max)	*****	*****	****

FIG. 7

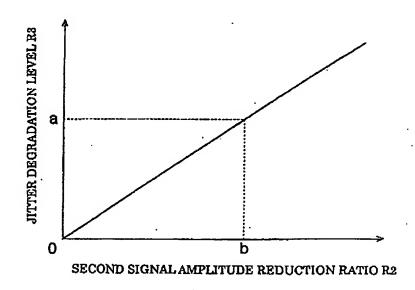
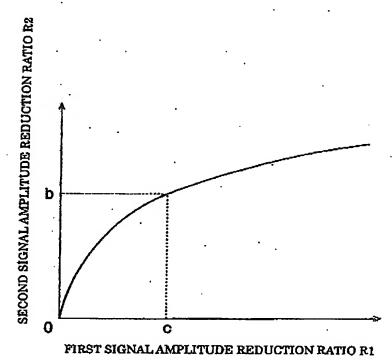


FIG. 8



·
52·····SPINDLE MOTOR
53······HEAD
54······CONTROLLER
55······LASER DRIVING CIRCUIT
56·····LENS DRIVING CIRCUIT
57FOCUS SERVO CIRCUIT
58·····TRACKING SERVO CIRCUIT
59······LASER CONTROL CIRCUIT
S1······RECORDING TEST SIGNAL
S2·····REPRODUCING TEST SIGNAL RECORDED ON
SECOND TRACK
S3MEASURING PREDETERMINED SIGNAL CHARACTERISTICS
S4······SIGNAL CHARACTERISTICS SATISFIES REFERENCE
CONDITIONS?
S5CHANGING RECORDING POWER PWAND RECORDING TEST
SIGNAL
S6······REPRODUCING TEST SIGNALS RECORDED ON SECOND
TRACK AND THIRD TRACK
S7MEASURING AMPLITUDE OF SIGNAL
S8CALCULATING FIRST SIGNAL AMPLITUDE REDUCTION
RATIO R1
S9R1 IS EQUAL TO OR LOWER THAN RC?
S10LOWERING RECORDING POWER PWAND RECORDING TEST
SIGNAL
S11DETERMINING OPTIMUM RECORDING POWER PW
S23······RECORDING TEST SIGNAL
S24REPRODUCING TEST SIGNALS RECORDED ON SECOND
TRACK AND THIRD TRACK
S25MEASURING JITTER AND AMPLITUDE OF SIGNAL
S27······RECORDING TEST SIGNAL
S29REPRODUCING TEST SIGNAL RECORDED ON SECOND TRACE
S30MEASURING JITTER AND AMPLITUDE OF SIGNAL
S33PRODUCING TABLE T
S34······PRODUCING FIRST GRAPH
S85PRODUCING SECOND GRAPH
S36······DETERMINING RC